*Extending the Mesh Independence For Solving Nonlinear Equations Using Restricted Domains* 

# Ioannis K. Argyros, Soham M. Sheth, Rami M. Younis, Á. Alberto Magreñán & Santhosh George

### International Journal of Applied and Computational Mathematics

ISSN 2349-5103 Volume 3 Supplement 1

Int. J. Appl. Comput. Math (2017) 3:1035-1046 DOI 10.1007/s40819-017-0398-1



🖉 Springer

ISSN: 2349-5103 e-ISSN: 2199-5796



Your article is protected by copyright and all rights are held exclusively by Springer (India) Private Ltd.. This e-offprint is for personal use only and shall not be selfarchived in electronic repositories. If you wish to self-archive your article, please use the accepted manuscript version for posting on your own website. You may further deposit the accepted manuscript version in any repository, provided it is only made publicly available 12 months after official publication or later and provided acknowledgement is given to the original source of publication and a link is inserted to the published article on Springer's website. The link must be accompanied by the following text: "The final publication is available at link.springer.com".



Int. J. Appl. Comput. Math (2017) 3 (Suppl 1):S1035–S1046 DOI 10.1007/s40819-017-0398-1



ORIGINAL PAPER

## **Extending the Mesh Independence For Solving Nonlinear Equations Using Restricted Domains**

Ioannis K. Argyros<sup>1</sup> · Soham M. Sheth<sup>2</sup> · Rami M. Younis<sup>2</sup> · Á. Alberto Magreñán<sup>3</sup> · Santhosh George<sup>4</sup>

Published online: 8 August 2017 © Springer (India) Private Ltd. 2017

**Abstract** The mesh independence principle states that, if Newton's method is used to solve an equation on Banach spaces as well as finite dimensional discretizations of that equation, then the behaviour of the discretized process is essentially the same as that of the initial method. This principle was inagurated in Allgower et al. (SIAM J Numer Anal 23(1):160–169, 1986). Using our new Newton–Kantorovich-like theorem and under the same information we show how to extend the applicability of this principle in cases not possible before. The results can be used to provide more efficient programming methods.

Keywords Newton's method · Banach space · Operator equation · Mesh independence

Mathematics Subject Classification 90C33 · 65J15 · 65 B05 · 65L50 · 65M50 · 49M15

Santhosh George sgeorge@nitk.ac.in

Ioannis K. Argyros iargyros@cameron.edu

Soham M. Sheth soham-sheth@utulsa.edu

Rami M. Younis rami-younis@utulsa.edu

Á. Alberto Magreñán alberto.magrenan@unir.net

- <sup>1</sup> Department of Mathematicsal Sciences, Cameron University, Lawton, OK 73505, USA
- <sup>2</sup> The University of Tulsa, Tulsa, OK 74104, USA
- <sup>3</sup> Department of Mathematics, Universidad Internacional de La Rioja, C/Gran Vía 41, 26005 Logroño, La Rioja, Spain
- <sup>4</sup> Department of Mathematical and Computational Sciences, NIT Karnataka, Mangalore 575025, India

#### Introduction

We are interested in the problem of locating a solution  $x^*$  of equation

$$F(x) = 0. \tag{1}$$

Here, X, Y denote Banach spaces,  $D \subseteq X$  is open, convex and  $F : D \subseteq X \longrightarrow Y$  is differentiable in the sense of Fréchet.

Newton's method is defined for n = 0, 1, 2, ..., by

$$x_{n+1} = x_n - F'(x_n)^{-1} F(x_n),$$
(2)

converges quadratically to  $x^*$  under certain conditions. However the iterates cannot be found easily in general. That is why we introduce a family of discretized equations

$$P_h(y) = 0 \tag{3}$$

indexed by some positive real number h with  $P_h : X_h \longrightarrow Y_h$  and  $X_h, Y_h$  being of finite dimension. Define the discretization on X by bounded linear operators  $L_h : X \to X_h$ , and introduce the family of discretized iterations by

$$y_0^h = L_h(x_0), \ y_{n+1}^h = y_n^h - P'_h(y_n^h)^{-1} P_h(y_n^h) \ (n \ge 0).$$
 (4)

In the elegant paper [3] they showed the relationship between distances  $||x_{n+1}-x_n||$ ,  $||y_{n+1}^n - y_n^n||$ ,  $||x_n - x^*||$ ,  $||y_n^h - y_h^*||$   $(n \ge 0)$  and the connection between the two iterations.

One of the basic assumptions was the Lipschitz continuity of operators F',  $P'_h(h > 0)$ . Here instead we use a combination of Lipschitz and center-Lipschitz conditions. This way the error bounds are improved, the minimum *n* for which  $||x_n - x^*|| \le \varepsilon$  holds can be smaller and the radius of convergence larger [2,3,7,9,12,13,16–22,25,26,28,30–33]. Other studies can be found in [1–33].

#### **Mesh Independence Principle**

Let  $U(v, \xi)$  and  $\overline{U}(v, \xi)$  stand respectively for the open and closed balls in X with center  $v \in X$  and of radius  $\xi > 0$ . Let  $x_0 \in D$  and R > 0. Define

$$R_0 = \sup\{t \in [0, R) : U(x_0, t) \subseteq D\}$$

We will need the following semilocal and local convergence theorems.

**Theorem 1** Let  $F : U(x_0, R_0) \subseteq X \rightarrow Y$  be a differentiable operator in the sense of *Fréchet*. Assume the existence of parameters n > 0,  $\ell_0 > 0$  such that

$$F'(x_0)^{-1} \in L(Y, X),$$
 (1)

$$\|F'(x_0)^{-1}F(x_0)\| \le \eta \tag{2}$$

and

$$\|F'(x_0)^{-1}[F'(x) - F'(x_0)]\| \le \ell_0 \|x - x_0\|.$$
(3)

Moreover, assume the existence of  $\ell > 0$  such that

$$\|F'(x_0)^{-1}[F'(x) - F'(y)]\| \le \ell \|x - y\| \text{ for all } x, y \in U(x_0, R_0) \cap U\left(x_0, \frac{1}{\ell_0}\right) := U,$$
(4)

Springer

 $t^* \leq R_0$ ,

#### Int. J. Appl. Comput. Math (2017) 3 (Suppl 1):S1035-S1046

(6)

$$L\eta \le 1 \tag{5}$$

where

$$t^{*} = \lim_{n \to \infty} t_{n} \le t^{**}$$

$$t^{**} = \left[1 + \frac{\ell_{0}\eta}{2(1-\alpha)(1-\ell_{0}\eta)}\right]\eta \le 2b\eta,$$

$$L = \frac{1}{4}\left(\sqrt{\ell_{0}\ell} + 4\ell_{0} + \sqrt{\ell\ell_{0} + 8\ell_{0}^{2}}\right)$$

$$b = \frac{1}{2}\left[1 + \frac{1}{2(1-\alpha)}\right]$$
(7)

and

$$\alpha = \frac{2\ell}{\ell + \sqrt{\ell^2 + 8\ell_0\ell}}.$$

$$t_{0} = 0, \ t_{1} = \eta, \ t_{2} = t_{1} + \frac{\ell_{0}(t_{1} - t_{0})^{2}}{2(1 - \ell_{0}t_{1})}$$
$$t_{n+2} = t_{n+1} + \frac{\ell(t_{n+1} - t_{n})^{2}}{2(1 - \ell_{0}t_{n+1})} \ (n \ge 1).$$
(8)

Then,  $\lim_{n\to\infty} x_n = x^* \in \overline{U}(x_0, t^*)$  for some  $x^*$ ,  $F(x^*) = 0$ , so that the following items hold

$$\|x_{n+2} - x_{n+1}\| \le \frac{\ell \|x_{n+1} - x_n\|^2}{2[1 - \ell_0 \|x_{n+1} - x_0\|]} \le t_{n+2} - t_{n+1}$$
(9)

and

$$\|x_n - x^*\| \le t^* - t_n.$$
<sup>(10)</sup>

Moreover, the solution  $x^*$  is unique in  $\overline{U}(x_0, t^*)$ , and if there exists  $R > t^*$  such that

$$U(x_0, R) \subseteq D \tag{11}$$

and

$$\ell_0(t^* + R) \le 2,\tag{12}$$

then, the solution  $x^*$  is unique in  $U(x_0, R)$ .

*Proof* Simply notice that the iterates  $x_n$  remain in U which is a more precise location than  $U(x_0, R_0)$  used in [17], since  $U \subseteq U(x_0, R_0)$ . Based on this observation the proof is analogous to the one in [17].

For  $x^*$  such that  $F(x^*) = 0$ , let

$$R_1 = \sup\{t \in [0, R) : U(x^*, t) \subseteq D\}.$$

**Theorem 2** Let  $F : D \subseteq X \to Y$  differentiable in the sense of Fréchet. Assume: there exist a simple zero  $x^* \in D$ , of equation F(x) = 0 and parameter  $\gamma_0 > 0$  such that

$$\|F'(x^*)^{-1}[F'(x) - F'(x^*)]\| \le \gamma_0 \|x - x^*\| \text{ for all } x \in U(x^*, R_1),$$
(13)

Moreover suppose that there exists  $\gamma > 0$  such that

$$\|F'(x^*)^{-1}[F'(x) - F'(y)]\| \le \gamma \|x - y\| \text{ for all } x, y \in U_1 := U(x^*, R_1) \cap U\left(x^*, \frac{1}{\gamma_0}\right),$$
(14)

and

$$\gamma_1 \le R_1,\tag{15}$$

where

$$\gamma_1 = \frac{2}{2\gamma_0 + \gamma}.\tag{16}$$

Then,  $\lim_{n\to\infty} x_n = x^* \in \overline{U}(x_0, \gamma_1)$ ,  $x^*$  is the only solution in  $\overline{U}(x^*, \gamma_1)$  and

$$\|x_{n+1} - x^*\| \le \frac{\gamma \|x_n - x^*\|^2}{2[1 - \gamma_0 \|x_n - x^*\|]}.$$
(17)

*Proof* Notice that iterates remain in  $U_1$ . This is a better location for the iterates  $x_n$  than  $U(x^*, R_1)$  used in [4]. Then, the proof follows exactly as the corresponding one in [4].

*Remark 3* The preceding results improve the corresponding ones in [17] and [4] which in turn improved the corresponding ones in [2,3]. Indeed, we have:

#### Semilocal Convergence (Theorem 1)

The Lipschitz condition corresponding to (4) and used in [2,3,17] is given by: there exists  $\ell_1 > 0$  such that

$$\|F'(x_0^*)^{-1}[F'(x) - F'(y)]\| \le \ell_1 \|x - y\| \text{ for each } x, y \in U(x_0, R_0).$$
(2.4')

Then, the conclusions of Theorem 1 were obtained as in [17] using  $\ell_1$  instead of  $\ell$ . Notice however that

 $\ell_0 \leq \ell$ 

and in particular

$$\ell \leq \ell_1$$

hold. If  $\ell = \ell_1$  our results reduce to the corresponding ones in [17]. But if  $\ell < \ell_1$ , then the new results have the following advantages over the ones in [17]:

i. Weaker sufficient convergence criteria. Indeed, the old criteria are given by

$$L_1 \eta \le 1, \tag{2.5'}$$

where

$$L_1 = \frac{1}{4} \left( \sqrt{\ell_0 \ell_1} + 4\ell_0 + \sqrt{\ell_1 \ell_0 + 8\ell^2} \right).$$

D Springer

#### Int. J. Appl. Comput. Math (2017) 3 (Suppl 1):S1035-S1046

Notice that

$$L_1\eta \leq 1 \implies L\eta \leq 1$$

but not necessarily vice versa, unless if  $\ell_0 = \ell_1$ .

ii More precise error estimates on the distances  $||x_{n+1}-x_n||$ ,  $||x_n-x^*||$ . Indeed the majorizing sequence given in [17] is defined by

$$u_0 = 0, \ u_1 = \eta, \ u_2 = u_1 + \frac{\ell_0 (u_1 - u_0)^2}{2(1 - \ell_0 u_1)},$$
  
 $u_{n+2} - u_{n+1} + \frac{\ell_1 (u_{n+1} - u_n)^2}{2(1 - \ell_0 u_{n+1})}$  for each  $n = 1, 2, \dots$ 

Then, a simple inductive argument shows that

$$t_n \le u_n$$
  

$$t_{n+1} - t_n \le u_{n+1} - u_n$$
  
and 
$$t^* \le u^* = \lim_{n \to \infty} u_n.$$

Strict inequality holds in the first two inequalities, if  $\ell < \ell_1$  and n = 3, 4, ... The last inequality shows that the information on the location of the solution is more precise, since  $t^* \le u^*$ .

#### Local Convergence (Theorem 2)

The Lipschitz condition corresponding to (14) and used in [4] is given by: there exists  $\bar{\gamma} > 0$  such that

$$\|F'(x^*)^{-1}[F'(x) - F'(y)]\| \le \bar{\gamma} \|x - y\| \text{ for each } x, y \in U(x^*, R_1).$$
(2.14)

Then, again in view of (14) and (2.14'), we get that

 $\gamma \leq \bar{\gamma}$ 

hold. The radius of convergence in [4] is given by

$$\bar{\gamma}_1 := \frac{2}{2\gamma_0 + \bar{\gamma}}$$

Then, we have

 $\bar{\gamma}_1 \leq \gamma_1$ 

and, if  $\gamma < \overline{\gamma}$ , then

$$\bar{\gamma}_1 < \gamma_1.$$

The corresponding error bound in [4] using  $\bar{\gamma}$  instead of  $\gamma$  is given by

$$\|x_{n+1} - x^*\| \le \frac{\bar{\gamma} \|x_n - x^*\|^2}{2[1 - \gamma_0 \|x_n - x^*\|]}.$$
(2.17)

In view of (17) and (2.17') we deduce that the new error bounds are more precise than the old ones leading to fewer iterations in order to obtain a certain desired error tolerance. Finally, notice that no additional computational effort is required because if we find  $\ell_1$ , we also find special cases  $\ell_0$  and  $\ell$ . The same is true for the constants  $\bar{\gamma}$ ,  $\gamma_0$  and  $\gamma$ .

Deringer

**Definition 4** As in [3,12] let  $S^* \subseteq X$  be such that

$$x^* \in S^*, x_n \in S^*, x_n - x^* \in S^*, x_{n+1} - x_n \in S^*, n \ge 0.$$
 (18)

Consider the family

$$\{P_h, L_h, \hat{L}_h\}, h > 0,$$
 (19)

where

$$P_h: D_h \to \hat{Y}_h, \tag{20}$$

$$L_h: X \to X_h, \ \hat{L}_h: Y \to \hat{Y}_h$$
 (21)

such that

$$L_h(S^* \cap U^*) \subseteq D_h. \tag{22}$$

The discretization family (19) is Lipschitz-center, Lipschitz uniform if there exist  $\rho > 0$ ,  $\ell_0 = \ell_0(h) > 0$  so that

$$U(L_h(x^*), \rho) \subseteq D_h, \tag{23}$$

$$\|P_{h}'(u) - P_{h}'(L_{h}(x^{*}))\| \le \ell_{0} \|u - L_{h}(x^{*})\|, \ u \in \overline{U}(L_{h}(x^{*}), \rho)$$
(24)

and  $\ell = \ell(h) > 0$  such that

$$\|P'_{h}(u) - P'_{h}(v)\| \le \ell \|u - v\|, \ u, v \in \overline{U}\left(L_{h}(x^{*}), \rho\right) \cap U(L_{h}(x^{*}), \frac{1}{\ell_{0}}\right) := U_{h}.$$
 (25)

Moreover (19) is: bounded if there exists a constant q > 0 so that

$$\|L_h(u)\| \le q \|u\|, \ u \in S^*,$$
(26)

stable: if there exists a  $\sigma > 0$  such that

$$\|P_h'(L_h(u))^{-1}\| \le \sigma, \ u \in S^* \cap U^*,$$
(27)

and consistent of order p:, if there exist  $c_0 > 0$ ,  $c_1 > 0$ ,  $c_2 > 0$  so that

$$\|\hat{L}_h(F(x^*)) - P_h(L_h(x^*))\| \le c_0 h^p,$$
(28)

$$\|\hat{L}_h(F(x)) - P_h(L_h(x))\| \le c_1 h^p, \ x \in S^* \cap U^*,$$
(29)

and

$$\|\hat{L}_h(F'(x))(y) - P'_h(L_h(x))L_h(y)\| \le c_2 h^p,$$
(30)

 $x \in S^* \cap U^*$ ,  $y \in S^*$ . We can show the following result for (3) and (4).

**Theorem 5** Let  $F : D \subseteq X \rightarrow Y$  be an operator satisfying hypotheses of Theorem 2 such that a Lipschitz, center-Lipschitz uniform discretization (19) exists which is bounded, stable and consistent of order p. Then

#### Int. J. Appl. Comput. Math (2017) 3 (Suppl 1):S1035-S1046

(a) Equation (3) has a solution which is locally unique with

$$y_h^* = L_h(x^*) + O(h^p),$$
 (31)

for each h such that

$$0 < h \le h_0 = \max\left\{ \left(\frac{\rho}{2bc_0\sigma}\right)^{1/p}, \left(\frac{1}{c_0\sigma^2 L}\right)^{1/p} \right\};'$$
 (32)

(b) There exist  $h_1 \in (0, h_0]$ ,  $r_1 \in (0, r^*]$  such that Newton's method (4) converges to  $y_h^*$ ; and for all  $k \ge 0$ 

$$y_k^h = L_h(x_k) + O(h^p),$$
 (33)

$$P_{h}(y_{k}^{h}) = \hat{L}_{h}(F(x_{k})) + O(h^{p})$$
(34)

$$y_k^h - y_h^* = L_h(x_k - x^*) + O(h^p)$$
 (35)

for each  $h \in (0, h_1]$  and  $x_0 \in U(x^*, r_1)$ .

Proof We showed in Theorem 1 that when

$$\alpha(h) = L\sigma \|P'_h(L_h(x^*))^{-1} P_h(L_h(x^*))\| \le 1,$$
(36)

$$r(h) \le 2b \| P'_h(L_h(x^*))^{-1} P_h(L_h(x^*)) \| \le \rho,$$
(37)

then Eq. (3) has a solution  $y_h^*$  which is unique in  $\overline{U}(L_h(x^*), r(h))$ . Using (36), (27), (28) and (32) we get in turn

$$\begin{aligned} \alpha(h) &\leq L\sigma^2 \|P_h(L_h(x^*))\| \\ &= L\sigma^2 \|P_h(L_h(x^*)) - \hat{L}_h(F(x^*))\| \\ &\leq L\sigma^2 c_0 h^p \leq 1 \end{aligned}$$
(38)

and

$$r(h) \le 2bc_0 h^p \le \rho \tag{39}$$

which hold by the choice of h given by (32). Hence (31) follows from

$$y_h^* - L_h(x^*) \| \le r(h) \le 2b\sigma c_0 h^p.$$
(40)

By Theorem 2 Newton's method (4) converges to  $y_h^*$  if

$$\|L_h(x_0) - y_h^*\| < \frac{2}{(2\ell_0 + \ell)} \|P_h'(y_h^*)^{-1}\|,$$
(41)

and

$$\overline{U}(y_h^*, \|L_h(x_0) - y_h^*\| \subseteq \overline{U}(L_h(x^*), \rho).$$
(42)

Estimate (42) holds, if

$$\|y_h^* - L_h(x^*)\| + \|L_h(x_0) - y_h^*\| \le \rho.$$
(43)

Deringer

By (26) and (38) we can have

$$\begin{aligned} \|L_h(x_0) - y_h^*\| &\leq \|L_h(x_0) - L_h(x^*)\| + \|L_h(x^*) - y_h^*\| \\ &\leq q \|x_0 - x^*\| + 2b\sigma c_0 h^p. \end{aligned}$$
(44)

Therefore (42) holds if

$$q \|x_0 - x^*\| + 4b\sigma c_0 h^p \le \rho.$$
(45)

Using the identity and the Banach perturbation Lemma [7,9,17,29]

$$P'_{h}(y_{h}^{*}) = P'_{h}(L_{h}(x^{*}))[I - P'_{h}(L_{h}(x^{*}))^{-1}(P'_{h}(L_{h}(x^{*})) - P'_{h}(y_{h}^{*}))]$$
(46)

we get

$$\|P_{h}'(y_{h}^{*})^{-1}\| \leq \frac{\|P_{h}'(L_{h}(x^{*}))^{-1}\|}{1 - \ell_{0}\|P_{h}'(L_{h}(x^{*}))^{-1}\|\|L_{h}(x^{*}) - y_{h}^{*}\|}$$
(47)

$$\leq \frac{\sigma}{1 - 2b\ell_0 \sigma^2 c_0 h^p}.\tag{48}$$

Hence (41) holds if

$$q \|x_0 - x^*\| + 4b\sigma c_0 h^p < \frac{2(1 - 2b\ell_0 c_0 \sigma^2 h^p)}{(2\ell_0 + \ell)\sigma}.$$
(49)

Choose

$$h_2 = \min\left\{ \left(\frac{\rho}{8bc_0\sigma}\right)^{1/p}, \left(\frac{1}{4bc_0\sigma(1+\ell_0\sigma)}\right)^{1/p} \right\};$$
(50)

and

$$r_2 = \min\left\{\frac{\rho}{2q}, \frac{1}{(2\ell_0 + \ell)q\sigma}\right\}.$$
(51)

Then (41) and (42) hold for each  $h \in (0, h_2]$  and  $x_0 \in U(x^*, r_2)$ . That is for these choices of h and  $x_0$ , Newton's method (4) converges to  $y_h^*$ . Define

$$h_1 = \min\left\{h_2, \left[\frac{1}{4\sigma^2(c_1 + c_2)(2\ell_0 + \ell)}\right]^{1/p}\right\}$$
(52)

$$r_1 = \min\left\{r_2, \frac{1}{4\ell\sigma q}\right\}.$$
(53)

With the above choice equation in  $\lambda$ 

$$\frac{\sigma}{1-\ell_0\sigma\lambda} \left[ \frac{\ell}{2} \lambda^2 + 2\ell q \|x_0 - x^*\|\lambda + (c_1 + c_2)h^p \right] = \lambda$$
(54)

is quadratic and has a positive solution, which satisfies

$$d \le 4\sigma (c_1 + c_2)h^p. \tag{55}$$

We now show using induction on *n* that for  $h \in (0, h_1)$ ,  $x_0 \in \overline{U}(x^*, r_1)$ , and all  $n \ge 0$ 

$$\|y_n^h - L_h(x_n)\| \le d \tag{56}$$

holds.

🖄 Springer

For n = 0 (56) holds. Assume (56) holds for n = 0, 1, ..., k. Using (4) we obtained the identity

$$y_{k+1}^{h} - L_{h}(x_{k+1}) = P_{h}'(y_{k}^{h})^{-1} \{ [P_{h}'(y_{k}^{h})(y_{k}^{h} - L_{h}(x_{k})) - P_{h}(y_{k}^{h}) + P_{h}(L_{h}(x_{k}))] + [(P_{h}'(y_{k}^{h}) - P_{h}'(L_{h}(x_{k})))L_{h}(F'(x_{k})^{-1}F(x_{k}))] + [P_{h}'(L_{h}(x_{k}))L_{h}(F'(x_{k})^{-1}F(x_{k})) - \hat{L}_{h}(F(x_{k}))] + [\hat{L}_{h}(F(x_{k})) - P_{h}(L_{h}(x_{k}))] \}.$$
(57)

As in (47) we get

$$\|P_{h}'(y_{k}^{h})^{-1}\| \leq \frac{\sigma}{1 - \ell_{0}\sigma \|y_{k}^{h} - L_{h}(x_{k})\|} \leq \frac{\sigma}{1 - \ell_{0}\sigma d}.$$
(58)

We can get in turn

$$\left\| P_{h}'(y_{k}^{h})(y_{k}^{h} - L_{h}(x_{k})) - P_{h}(y_{k}^{h}) + P_{h}(L_{h}(x_{k})) \right\| \leq \frac{\ell}{2} \left\| y_{k}^{h} - L_{h}(x_{k}) \right\|^{2} \leq \frac{\ell}{2} d^{2},$$
(59)

$$\|(P'_{h}(y^{h}_{k}) - P'_{h}(L_{h}(x_{k})))L_{h}(F'(x_{k})^{-1}F(x_{k}))\| \leq \ell q \|y^{h}_{k} - L_{h}(x_{k})\|\|x_{k+1} - x_{k}\| \leq 2\ell q d\|x_{0} - x^{*}\|,$$
(60)

(since  $||x_{k+1} - x^*|| \le ||x_k - x^*||$ )

$$\|P'_{h}(L_{h}(x_{k}))L_{h}(F'(x_{k})^{-1}F(x_{k})) - \hat{L}_{h}(F(x_{k}))\| \le c_{2}h^{p},$$
(61)

and

$$\|\hat{L}_h(F(x_k)) - P_h(L_h(x_k))\| \le c_1 h^p.$$
(62)

By (55) and (57)–(62) we get

$$\|y_{k+1}^h - L_h(x_{k+1})\| \le d \le 4\sigma (c_1 + c_2)h^p,$$
(63)

where d satisfies (54). Moreover by the Lipschitz continuity of  $P'_h$  there exists b such that

$$\|P'_h(x)\| \le b, \ x \in U_h.$$
 (64)

Therefore we can have

$$\|P_{h}(y_{k}^{h}) - \hat{L}_{h}(F(x_{k}))\| \leq \|P_{h}(y_{k}^{h}) - P_{h}(L_{h}(x_{k}))\| \\ + \|P_{h}(L_{h}(x_{k})) - \hat{L}_{h}(F(x_{k}))\| \\ \leq b\|y_{k}^{h} - L_{h}(x_{k})\| + c_{1}h^{p} \\ \leq 4\sigma b(c_{1} + c_{2})h^{p} + c_{1}h^{p} = c_{3}h^{p}$$
(65)

where  $c_3 = 4\sigma b(c_1 + c_2) + c_1$ . Furthermore by (40), (56) and (63) we get

$$\|y_{k}^{h} - y_{h}^{*} - L_{h}(x_{k} - x^{*})\| \leq \|y_{k}^{h} - L_{h}(x_{k})\| + \|y_{h}^{*} - L_{h}(x^{*})\| \\ \leq 4\sigma b(c_{1} + c_{2})h^{p} + 2b\sigma c_{0}h^{p} = ch^{p},$$
(66)

where  $c = 2\sigma (bc_0 + 2c_1 + 2c_2)$ .

The following result is the second part of the mesh independence principle.

Deringer

**Theorem 6** Suppose: hypotheses of Theorem 5 hold; there exists  $\mu > 0$  such that

$$\liminf_{h>0} \|L_h(x)\| \ge \mu \|x\| \text{ for } x \in S^*$$
(67)

Let  $\bar{r} \in (0, r_1]$  and each fixed  $\varepsilon > 0, x_0 \in \overline{U}(x^*, \bar{r})$ . Then,  $\bar{h} = \bar{h}(\varepsilon, h_1]$  can be obegintheoained such that

$$|\mu| \le 1 \tag{68}$$

for each  $h \in (0, \bar{h}]$ , where  $\mu = \min\{n \ge 0, \|x_n - x^*\| < \varepsilon\} - \min\{n \ge 0, \|y_n^h - y_h^*\| < \varepsilon\}$ .

*Proof* Let *k* be the unique integer satisfying

$$\|x_{k+1} - x^*\| < \varepsilon \le \|x_k - x^*\|,$$
(69)

and  $h_3 > 0$  (depending on  $x_0$ ) such that

$$\|L_h(x_k - x^*)\| \ge \mu \|x_k - x^*\| \text{ for all } h \in (0, h_3).$$
(70)

Define

$$\bar{r} = \max\left\{r_1, \frac{\beta}{2\sigma q \left(\ell + \beta \ell_0\right)}\right\}, \ \beta = \min\left\{\frac{1}{q}, \mu, 2q\right\},\tag{71}$$

and

$$\bar{h} = \min\left\{h_1, h_3, \left[\frac{\beta}{2\sigma c(\ell + \beta \ell_0)}\right]^{1/p}, \left(\frac{\mu \varepsilon}{2c}\right)^{1/p}\right\}.$$
(72)

By (66) and (72) we can get

$$\|y_{k+1}^h - y_h^*\| \le \|L_h(x_{k+1} - x^*)\| + ch^p \le q\varepsilon + \frac{\beta\varepsilon}{2} < 2q\varepsilon.$$

$$\tag{73}$$

Moreover from Theorem 2 we get

$$\begin{aligned} \|y_{k+1}^{h} - y_{h}^{*}\| &\leq \frac{\ell\sigma \|y_{k+1}^{h} - y_{h}^{*}\|^{2}}{2[1 - \ell_{0}\sigma \|y_{k+1}^{h} - y_{h}^{*}\|]} \\ &\leq \frac{\ell\sigma \|y_{0}^{h} - y_{h}^{*}\|}{2[1 - \ell_{0}\sigma \|y_{0}^{h} - y_{h}^{*}\|]} \|y_{k+1}^{h} - y_{h}^{*}\| \\ &< \frac{\ell\sigma (q\bar{r} + c\bar{h}^{p})}{1 - \ell_{0}\sigma (q\bar{r} + c\bar{h}^{p})} \\ &\leq \lambda q\varepsilon < \varepsilon. \end{aligned}$$
(74)

By (66) and (70)

$$\varepsilon \le \|x_k - x^*\| \le \frac{1}{\mu} \|L_h(x_k - x^*)\| \le \frac{1}{\mu} (\|y_k^h - y_h^*\| + c\bar{h}^p), \tag{75}$$

or

$$\|y_k^h - y_h^*\| \ge \mu\varepsilon - c\bar{h}^p \ge \mu\varepsilon - \frac{\mu\varepsilon}{2} = \frac{\mu\varepsilon}{2}.$$
(76)

Furthermore if  $||y_{k-1}^h - y_h^*|| < \varepsilon$ , we get

$$\|y_k^h - y_h^*\| < \frac{1}{2}\beta\varepsilon \le \frac{\mu\varepsilon}{2}$$
(77)

Deringer

contradicting (76). Hence we get

$$\|y_{k-1}^h - y_h^*\| \ge \varepsilon. \tag{78}$$

The result now follows from (69), (74) and (78).

Remark 7 The preceding results reduce to the corresponding ones in [3], when

$$\ell = \ell_0 \ and \ c_0 = c_1.$$
 (79)

Note though that (79) and

$$c_0 \le c_1 \tag{80}$$

hold. In case (74) or (80) hold as strict inequalities then it is clear that our smallest integer  $n_1$  satisfying  $||x_n - x^*|| < \varepsilon$  is smaller than the corresponding integer  $n_2$  given in the references mentioned above. Hence we require less computational steps to achieve the same error tolerance  $\varepsilon$  than before. The ratios in relationships (33)–(35) are also finer.

Note that the improvements made through our Theorem 1-6 are achieved under the same hypotheses as before. The rest of the works on the mesh independence principle listed in the references can also be improved along the same lines.

Remark 8 If (67) is replaced by the stronger but standard in most discretization studies condition

$$\lim_{h \to 0} \|L_h(x)\| = \|x\| \text{ uniformly for } x \in S^*,$$
(81)

then Theorem 6 still holds but  $\bar{h}_1$  does not depend on  $x_0$ . Note also that (68) follows from (81).

*Remark 9* As already noted in [2,3,7,9,11–23,25–33] the local results obtained here can be used to provide a more efficient programming for projection iteration methods such as Arnoldi's, the generalized minimum residual iteration method(GMRES), the generalized conjugate residual iteration method (GCR), for combined Newton/finite-difference projection iteration methods. Moreover, the results can be useful to solve mesh independence problems where the trapezoidal method, the box method and allocation iterations for boundary value problems are involved.

#### References

- 1. Adams, R.A., Sobolov Spaces, Academic Press (1975)
- Allgower, E.L., Mccormik, S.T.F., Pryor, D.V.: A general mesh independence principle for Newton's method applied to second order boundary value problems. Computing 23(3), 233–246 (1979)
- Allgower, E.L., Böhmer, K., Potra, F.A., Rheinboldt, W.C.: A mesh independence principle for operator equations and their discretizations. SIAM J. Numer. Anal. 23, 160–169 (1986)
- Argyros, I.K.: A unifying local-semilocal convergence analysis and applications for two-point Newtonlike methods in Banach space. J. Math. Anal. Appl. 298, 374–397 (2004)
- Argyros, I.K.: On the Newton–Kantorovich hypothesis for solving equations. J. Comput. Appl. Math. 169, 315–332 (2004)
- Argyros, I.K.: Concerning the "terra incognita" between convergence regions of two Newton methods. Nonlinear Anal. 62, 179–194 (2005)
- 7. Argyros, I.K.: Convergence and application of Newton-type iterations. Springer, Berlin (2008)
- Argyros, I.K.: Approximating solutions of equations using Newton's method with a modified Newton's method iterate as a starting point. Rev. Anal. Numer. Theor. Approx. 36, 123–138 (2007)

п

## Author's personal copy

- Argyros, I.K.: Computational Theory of Iterative Methods. Series: Studies in Computational Mathematics, 15, In: Chui, C.K., Wuytack, L., Elsevier Publ. Co. New York, U.S.A (2007)
- Argyros, I.K.: On a class of Newton-like methods for solving nonlinear equations. J. Comput. Appl. Math. 228, 115–122 (2009)
- Argyros, I.K.: A Semilocal convergence for directional Newton methods. Math. Comput. (AMS) 80, 327–343 (2011)
- Argyros, I.K.: On a new Newton-Mysovskii-type theorem with applications to inexact Newton-like methods and their discretizations. IMA J. Numer. Anal. 18(1), 37–56 (1998)
- Argyros, I.K., Hilout, S.: Enclosing roots of polynomial equations and their applications to iterative processes. Surv. Math. Appl. 4, 119–132 (2009)
- Argyros, I.K., Hilout, S.: Extending the Newton–Kantorovich hypothesis for solving equations. J. Comput. Appl. Math. 234, 2993–3006 (2010)
- Argyros, I.K., Hilout, S., Tabatabai, M.A.: Mathematical Modelling with Applications in Biosciences and Engineering. Nova Publishers, New York (2011)
- Argyros, I.K., Cho, Y., Hilout, S.: Numerical Methods for Equations and Its Applications. CRC Press, Taylor and Francis, New York (2012)
- Argyros, I.K., Hilout, S.: Weaker conditions for the convergence of Newton's method. J. Complex. 28, 364–387 (2012)
- Axelsson, O.: On global convergence of iterative methods. In: Iterative Solution of Nonlinear Systems of Equations, pp. 1–19, Lecture Notes in Math. 953, Springer (1982)
- Axelsson, O.: On mesh independence and Newton-type methods. In: Proceedings of ISNA'92-International Symposium on Numerical Analysis, Part I (Prague, 1992), Appl. Math. 38, no. 4-5, pp. 249–265 (1993)
- Axelsson, O., Layton, W.: A two-level discretization of nonlinear boundary value problems. SIAM J. Numer. Anal. 33(6), 2359–2374 (1996)
- 21. Blaheta, R.: Multilevel Newton methods for nonlinear problems with applications to elasticity, Copernicus 940820, Technical report
- Brown, P.N., Vassilevski, P.S., Woodward, C.S.: On mesh-independence of an inexact Newton-multigrid algorithm. SIAM J. Sci. Comput. 25(2), 570–590 (2003)
- 23. Ciarlet, P.G.: The Finite Element Method for Elliptic Problems. North-Holland, Amsterdam (1978)
- Dembo, R.S., Eisenstat, S.C., Steihaug, T.: Inexact Newton methods. SIAM J. Numer. Anal. 19(2), 400–408 (1982)
- Deuflhard, P., Potra, F.A.: Asymptotic mesh independence of Newton–Galerkin methods via a refined Mysovskii theorem. SIAM J. Numer. Anal. 29(5), 1395–1412 (1992)
- Faragó, I., Karátson, J.: Numerical solution of nonlinear elliptic problems via preconditioning operators. Theory and applications. Adv. Comput., Vol. 11, NOVA Science publishers, New York (2002)
- 27. Federer, H.: Geometric Measure Theory. Springer, New York (1969)
- Hintermüller, M., Ulbrich, M.: A mesh-independence result for semismooth Newton methods. Math. Program. 101(1), 151–184 (2004)
- 29. Kantorovich, L.V., Akilov, G.P.: Functional Analysis. Pergamon Press, Oxford (1982)
- Karátson, J., Faragó, I.: Variable preconditioning via quasi-Newton methods for nonlinear problems in Hilbert spaces. SIAM J. Numer. Anal. 41(4), 1242–1262 (2003)
- Kelley, C.T.: Iterative Methods for Linear and Nonlinear Equations. Frontiers in Appl. Math. SIAM, Philadelphia (1995)
- Kelley, C.T., Sachs, E.W.: Mesh independence of Newton-like methods for infinite-dimensional problems. J. Integral Equ. Appl. 3(4), 549–573 (1991)
- Kim, T., Pasciak, J.E., Vassilevski, P.S.: Mesh-independence of the modified inexact Newton method for a second order non-linear problem. Numer. Linear Algebra. Appl. 13(1), 23–47 (2006)